#### **Advanced Physics Lab – Errors and Uncertainties**

Advanced Physics Lab, PHYS 3600 Don Heiman, Northeastern University, 2021

#### This Week

**1a-INTRO-a & 1b-INTRO-b: Introduction to the Course** motivation, boiler plate (syllabus/labs) Fermi questions, exercises

2-ERRORS: Errors and Uncertainties accuracy, precision, round off, propagation of errors

**3-OPTICS: Optical Properties** EM spectrum, photo detectors, light emitters

**4-SEMICOND: Semiconductors** 

band gap, Fermi energy, resistivity, Hall effect

**5-ACOUSTICS:** 

sound, beats, Fourier transform, music

**6-EXPERIMENTS: Intro to Lab Experiments** *Virtual tour my research lab* 

## **Errors and Uncertainties**

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Notes are on the website

- 1. Precision versus Accuracy
- 2. Types of Errors
- 3. Significant Digits and Round-off
- 4. Mean and Standard Deviation
- 5. Propagation of Errors
- 6. Interpolation
- 7. Smoothing y(x) Curves

#### **Precision versus Accuracy**

1.1 Precision  $\rightarrow$ 

 How *exact* is a measurement, or how "fine" is the scale (# of significant figures) – does not mean it is correct (also referred to as repeatability or reproducibility)

Suppose you measure a resistor with a digital ohmmeter. The ohmmeter reads  $1.53483 \Omega$ . This number has a high *precision*. However, it may not represent the "true" resistance as the wires connecting the resistor and ohmmeter have some small resistance that contributes to the measurement.

#### 1.2 Accuracy $\rightarrow$

#### - How *close* is a measurement to the "true" value

Accuracy is a measure of the *correctness* of the measurement. To determine a more *accurate* value for the resistor's resistance, you could measure the resistance of the wires and subtract it.

#### Precise and Accurate $\rightarrow$







# **Types of Errors**

We often want to know how close we are to the truth. The *error* is simply the **quantifiable difference** between the value obtained in real life and the "*true*" value.

There are three main categories of errors:

blunders, systematic errors, and random errors.

**2.1 Blunders** – These can usually be avoided by examining the results as you proceed with measurements.

Examples: reading and recording the wrong scale on the instrument, such as **millivolts instead of volts**; reading **milliseconds instead of microseconds** on the oscilloscope time base; forgetting to convert frequency "f" in cycles/second (Hz) to " $\omega$ " in radians/second; or mixing up **centimeters and inches**.

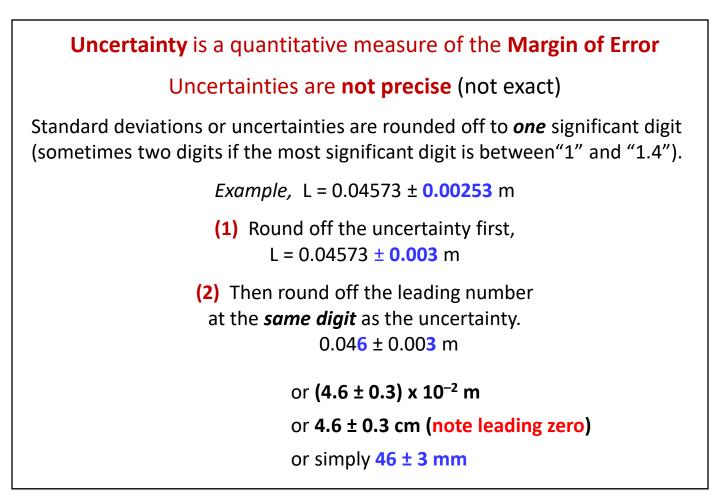
#### **2.2 Systematic Errors** – these are "**reproducible**" errors from faulty calibration or biased observation.

They can often be estimated from analysis of the experimental techniques. If you are measuring a distance with an **incorrect ruler** (shortened or lengthened), you can calibrate the ruler and make the correction by multiplying the original distances by a calibration factor.

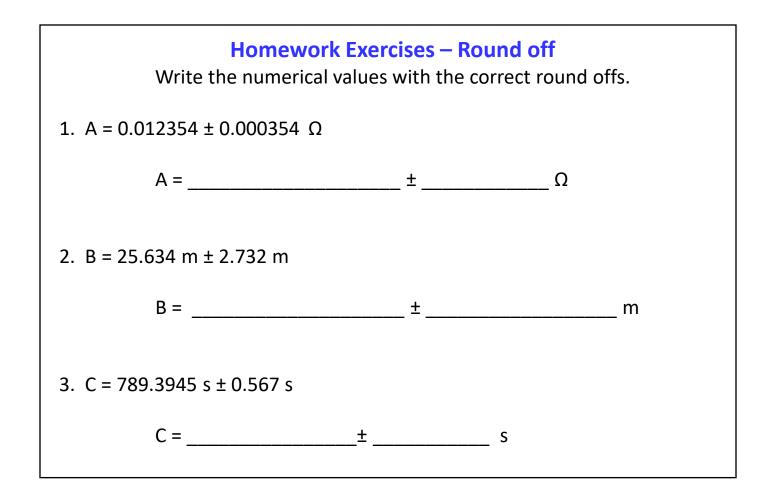
**2.3 Random Errors** – these are due to fluctuations in measurements from repeated experiments.

Random errors are due to **statistical fluctuations**, often referred to as noise, or limited precision of an instrument. They can be minimized by repeating the experiment many times. Note that random errors which are small produce high precision, but not necessarily high accuracy. The precision usually increases only as the **square root** of the measurement time or number of measurements.

## **Uncertainty, Significant Digits and Round-off**



### **Uncertainty, Significant Digits and Round-off**



#### 5.1 Addition and Subtraction

 $z(x,y) = ax \pm by$ 

Given the function  $z(x,y) = ax \pm by$ , where x and y are not correlated and their standard deviations are  $\sigma_x$  and  $\sigma_y$ , the standard deviation in z is given by  $\sigma_y^2 = a^2 \sigma_y^2 + b^2 \sigma_y^2$ .

For example, compute the perimeter of a rectangle with sides  $H=2.0 \pm 0.2$  cm and  $W=3.5 \pm 0.4$  cm. The perimeter is P = H+H+W+W = 2H+2W=11.0 cm. The standard deviation in the perimeter is

 $\sigma_{\rm P}^2 = \frac{2^2 * \sigma_{\rm x}^2 + 2^2 * \sigma_{\rm y}^2}{\sigma_{\rm P}^2 = \frac{2^2 * 0.2^2 + 2^2 * 0.4^2}{\sigma_{\rm y}^2} = 0.9^2.$ 

Thus, the resulting perimeter is **P** = **11.0** ± **0.9** cm.

For simple addition of two numbers (z=x+y) the standard deviations are added in quadrature

 $\sigma_z^2 = \sigma_x^2 + \sigma_y^2$ .

#### Trick #1

**Eliminating negligible uncertainties** 

in quadrature addition/subtraction

```
Suppose that you are given the values
           A = 100 \pm 1
           B = 100 \pm 10
           C = 100 \pm 30
       The sum S = A+B+C = 300
        \sigma_{\rm s} = [1^2 + 10^2 + 30^2]^{1/2}
           = [1 + 100 + 900]^{1/2}
           = 31.6
           = 30 when rounded off
           = the largest uncertainty
Rule – eliminate uncertainties that are
       at least 3-times smaller.
```

5.2 Multiplication and Division

 $z(x,y) = ax^n y$  or  $z(x,y) = ax^n/y$ 

Given  $z(x,y) = ax^n y$  or  $z(x,y) = ax^n/y$ , where x and y are not correlated and their standard deviations, are  $\sigma_x$  and  $\sigma_{y'}$ then the standard deviation in z is determined by the *fractional* uncertainties,  $\sigma_x/x$  and  $\sigma_y/y$ .

 $(\sigma_z/z)^2 = n^2(\sigma_x/x)^2 + (\sigma_y/y)^2$ 

For example, compute the area of the rectangle with sides H=2.0  $\pm$  0.2 cm and W=3.5  $\pm$  0.4 cm. The area is A=HW=7.0 cm<sup>2</sup>. The standard deviation in the area is now

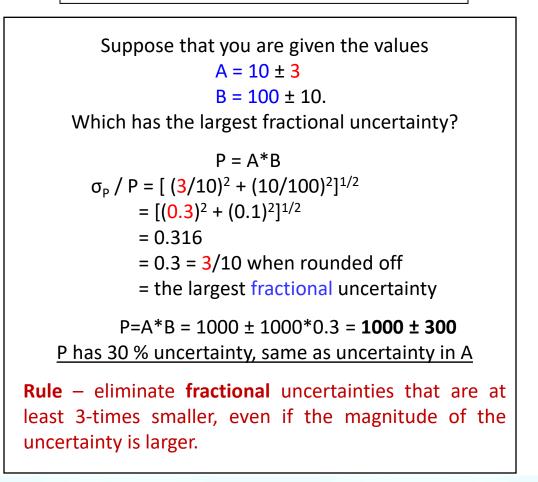
$$\sigma_{A}^{2} = A^{2} \left[ \left( \sigma_{x}^{2} / x^{2} \right) + \sigma_{y}^{2} / y^{2} \right] \sigma_{A}^{2} = A^{2} \left[ \left( 0.2^{2} / 2.0^{2} \right) + 0.4^{2} / 3.5^{2} \right] = 7^{2} * 0.15^{2}.$$

Thus, the resulting area is  $A=7 \pm 1 \text{ cm}^2$ .

#### Trick #2

**Eliminating negligible uncertainties** 

in quadrature multiplication/division



#### Generalization

For any function *F*(x,y,...), you can compute the total uncertainty using

 $\sigma_F^2 = (\partial F/\partial x)^2 \sigma_x^2 + (\partial F/\partial y)^2 \sigma_y^2 + \dots ,$ 

where the x,y... variables are independent and not correlated.

#### **5.3 Exponents**

For $z = a x^{\pm b}$ ,	$\sigma_z/z = b \sigma_x/x$
For $z = a e^{\pm bx}$ ,	$\sigma_z/z = b \sigma_x$
For z = a <i>ln</i> (±bx),	$\sigma_z = a \sigma_x / x.$

## **Summary - Propagation of Errors**

#### Addition/Subtraction

Eliminating negligible uncertainties in quadrature

Suppose that you are given the values  $A = 100 \pm 1$   $B = 100 \pm 10$  $C = 100 \pm 30$ 

The sum is S = A+B+C = 300

 $\sigma_{\rm S} = [1^2 + 10^2 + 30^2]^{1/2}$  $= [1 + 100 + 900]^{1/2}$ = 31.6

= 30 when rounded off

= the largest uncertainty

<u>Rule</u> – eliminate <u>uncertainties</u> that are at least 3-times smaller.

#### **Multiplication/Division**

Eliminating negligible uncertainties in quadrature

Suppose that you are given the values  $A = 10 \pm 3$  $B = 100 \pm 10$ The product is P = A \* B = 1000 $\sigma_{\rm P} / P = [(3/10)^2 + (10/100)^2]^{1/2}$  $= [(0.3)^2 + (0.1)^2]^{1/2}$  $= [0.09 + 0.01]^{1/2}$ = 0.316= 3/10 when rounded off = the largest fractional uncertainty Rule – eliminate fractional uncertainties that are at least 3-times smaller, even if the magnitude of

the uncertainty is larger.

