## Advanced Physics Lab - Errors and Uncertainties

> Advanced Physics Lab, PHYS 3600
> Don Heiman, Northeastern University, 2021
This Week

| 1a-INTRO-a \& 1b-INTRO-b: Introduction to the Course |
| :---: |
| motivation, boiler plate (syllabus/labs) |
| Fermi questions, exercises |

2-ERRORS: Errors and Uncertainties
accuracy, precision, round off, propagation of errors
3-OPTICS: Optical Properties
EM spectrum, photo detectors, light emitters
4-SEMICOND: Semiconductors
band gap, Fermi energy, resistivity, Hall effect
6-EXPERIMENTS: Intro to Lab Experiments
Virtual tour my research lab

## Errors and Uncertainties

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1. Precision versus Accuracy
2. Types of Errors
3. Significant Digits and Round-off
4. Mean and Standard Deviation
5. Propagation of Errors
6. Interpolation
7. Smoothing \(y(x)\) Curves

\section*{Precision versus Accuracy}

\subsection*{1.1 Precision \(\rightarrow\) \\ - How exact is a measurement, or how "fine" is the scale (\# of significant figures) - does not mean it is correct (also referred to as repeatability or reproducibility)}

Suppose you measure a resistor with a digital ohmmeter. The ohmmeter reads \(1.53483 \Omega\). This number has a high precision. However, it may not represent the "true" resistance as the wires
 connecting the resistor and ohmmeter have some small resistance that contributes to the measurement.

\subsection*{1.2 Accuracy \(\rightarrow\)}
- How close is a measurement to the "true" value

Accuracy is a measure of the correctness of the measurement. To determine a more accurate value for the resistor's resistance, you could measure the resistance of the wires and subtract it.

\section*{Precise and Accurate \(\rightarrow\)}

\section*{Types of Errors}

We often want to know how close we are to the truth. The error is simply the quantifiable difference between the value obtained in real life and the "true" value.
There are three main categories of errors:

\section*{blunders, systematic errors, and random errors.}
2.1 Blunders - These can usually be avoided by examining the results as you proceed with measurements.

Examples: reading and recording the wrong scale on the instrument, such as millivolts instead of volts; reading milliseconds instead of microseconds on the oscilloscope time base; forgetting to convert frequency " \(f\) " in cycles/second ( Hz ) to " \(\omega\) " in radians/second; or mixing up centimeters and inches.
2.2 Systematic Errors - these are "reproducible" errors from faulty calibration or biased observation.

They can often be estimated from analysis of the experimental techniques. If you are measuring a distance with an incorrect ruler (shortened or lengthened), you can calibrate the ruler and make the correction by multiplying the original distances by a calibration factor.
2.3 Random Errors - these are due to fluctuations in measurements from repeated experiments.

Random errors are due to statistical fluctuations, often referred to as noise, or limited precision of an instrument. They can be minimized by repeating the experiment many times. Note that random errors which are small produce high precision, but not necessarily high accuracy. The precision usually increases only as the square root of the measurement time or number of measurements.

\section*{Uncertainty, Significant Digits and Round-off}

Uncertainty is a quantitative measure of the Margin of Error
Uncertainties are not precise (not exact)
Standard deviations or uncertainties are rounded off to one significant digit (sometimes two digits if the most significant digit is between" 1 " and "1.4").

Example, \(\mathrm{L}=0.04573 \pm 0.00253 \mathrm{~m}\)
(1) Round off the uncertainty first,
\[
\mathrm{L}=0.04573 \pm 0.003 \mathrm{~m}
\]
(2) Then round off the leading number at the same digit as the uncertainty.
\[
0.046 \pm 0.003 \mathrm{~m}
\]
or \((4.6 \pm 0.3) \times 10^{-2} \mathbf{m}\)
or \(4.6 \pm 0.3 \mathbf{c m}\) (note leading zero)
or simply \(46 \pm 3 \mathrm{~mm}\)

\section*{Uncertainty, Significant Digits and Round-off}


\section*{Propagation of Errors}

\subsection*{5.1 Addition and Subtraction}
\[
z(x, y)=a x \pm b y
\]

Given the function \(\mathrm{z}(\mathrm{x}, \mathrm{y})=\mathrm{ax} \pm \mathrm{by}\), where x and y are not correlated and their standard deviations are \(\sigma_{x}\) and \(\sigma_{y}\), the standard deviation in \(z\) is given by
\[
\sigma_{z}^{2}=a^{2} \sigma_{x}{ }^{2}+b^{2} \sigma_{y}{ }^{2} .
\]

For example, compute the perimeter of a rectangle with sides \(\mathrm{H}=2.0 \pm 0.2 \mathrm{~cm}\) and \(\mathrm{W}=3.5 \pm 0.4 \mathrm{~cm}\). The perimeter is \(\mathrm{P}=\mathrm{H}+\mathrm{H}+\mathrm{W}+\mathrm{W}=2 \mathrm{H}+2 \mathrm{~W}=11.0 \mathrm{~cm}\).
The standard deviation in the perimeter is
\[
\begin{aligned}
& \sigma_{P}^{2}=2^{2 *} \sigma_{x}{ }^{2}+2^{2 *} \sigma_{v}{ }^{2} \\
& \sigma_{P}{ }^{2}=2^{2 *} 0.2^{2}+2^{2} * 0.4^{2}=0.9^{2} .
\end{aligned}
\]

Thus, the resulting perimeter is \(\mathbf{P}=\mathbf{1 1 . 0} \pm \mathbf{0 . 9} \mathbf{~ c m}\).
For simple addition of two numbers \((\mathrm{z}=\mathrm{x}+\mathrm{y})\) the standard deviations are added in quadrature
\[
\sigma_{z}^{2}=\sigma_{x}^{2}+\sigma_{y}^{2} .
\]

\section*{Propagation of Errors}

\section*{Trick \#1 \\ Eliminating negligible uncertainties \\ in quadrature addition/subtraction}

Suppose that you are given the values
\[
\begin{aligned}
& A=100 \pm 1 \\
& B=100 \pm 10 \\
& C=100 \pm 30
\end{aligned}
\]

The sum \(S=A+B+C=300\)
\[
\begin{aligned}
\sigma_{\mathrm{S}} & =\left[1^{2}+10^{2}+30^{2}\right]^{1 / 2} \\
& =[1+100+900]^{1 / 2} \\
& =31.6 \\
& =30 \text { when rounded off } \\
& =\text { the largest uncertainty }
\end{aligned}
\]

Rule - eliminate uncertainties that are at least 3-times smaller.

\section*{Propagation of Errors}

\subsection*{5.2 Multiplication and Division \\ \[
z(x, y)=a x^{n} y \text { or } z(x, y)=a x^{n} / y
\]}

Given \(\mathbf{z}(\mathbf{x}, \mathbf{y})=\mathbf{a} \mathbf{x}^{\mathrm{n}} \mathbf{y}\) or \(\mathbf{z}(\mathbf{x}, \mathbf{y})=\mathbf{a} \mathbf{x}^{\mathrm{n}} / \mathbf{y}\), where x and y are not correlated and their standard deviations, are \(\sigma_{x}\) and \(\sigma_{y}\), then the standard deviation in \(z\) is determined by the fractional uncertainties, \(\sigma_{x} / x\) and \(\sigma_{y} / y\).
\[
\left(\sigma_{z} / z\right)^{2}=n^{2}\left(\sigma_{x} / x\right)^{2}+\left(\sigma_{y} / y\right)^{2}
\]

For example, compute the area of the rectangle with sides \(\mathrm{H}=2.0 \pm 0.2\) cm and \(\mathrm{W}=3.5 \pm 0.4 \mathrm{~cm}\). The area is \(\mathrm{A}=\mathrm{HW}=7.0 \mathrm{~cm}^{2}\). The standard deviation in the area is now
\[
\begin{aligned}
& \sigma_{A}{ }^{2}=A^{2}\left[\left(\sigma_{x}{ }^{2} / x^{2}\right)+\sigma_{y}{ }^{2} / y^{2}\right] \\
& \sigma_{A}{ }^{2}=A^{2}\left[\left(0.2^{2} / 2.0^{2}\right)+0.4^{2} / 3.5^{2}\right]=7^{2} * 0.15^{2} .
\end{aligned}
\]

Thus, the resulting area is \(\mathbf{A}=\mathbf{7} \pm \mathbf{1} \mathbf{c m}^{\mathbf{2}}\).

\section*{Propagation of Errors}

\section*{Trick \#2 \\ Eliminating negligible uncertainties in quadrature multiplication/division}

Suppose that you are given the values
\[
\begin{aligned}
& A=10 \pm 3 \\
& B=100 \pm 10 .
\end{aligned}
\]

Which has the largest fractional uncertainty?
\[
\begin{aligned}
& P=A * B \\
& \sigma_{P} / P=\left[(3 / 10)^{2}+(10 / 100)^{2}\right]^{1 / 2} \\
&=\left[(0.3)^{2}+(0.1)^{2}\right]^{1 / 2} \\
&=0.316 \\
&=0.3=3 / 10 \text { when rounded off } \\
&=\text { the largest fractional uncertainty } \\
& P=A * B=1000 \pm 1000 * 0.3=1000 \pm \mathbf{3 0 0}
\end{aligned}
\]
\[
\text { Phas } 30 \text { \% uncertainty, same as uncertainty in A }
\]

Rule - eliminate fractional uncertainties that are at least 3-times smaller, even if the magnitude of the uncertainty is larger.

\section*{Propagation of Errors}


\section*{Summary - Propagation of Errors}

\section*{Addition/Subtraction}

Eliminating negligible uncertainties in quadrature

Suppose that you are given the values
\[
\begin{aligned}
& A=100 \pm 1 \\
& B=100 \pm 10 \\
& C=100 \pm 30
\end{aligned}
\]

The sum is \(S=A+B+C=300\)
\[
\begin{aligned}
\sigma_{\mathrm{S}} & =\left[1^{2}+10^{2}+30^{2}\right]^{1 / 2} \\
& =[1+100+900]^{1 / 2} \\
& =31.6 \\
& =30 \text { when rounded off } \\
& =\text { the largest uncertainty }
\end{aligned}
\]

Rule - eliminate uncertainties that are at least 3-times smaller.

\section*{Multiplication/Division}

Eliminating negligible uncertainties
in quadrature

Suppose that you are given the values
\[
\begin{aligned}
& A=10 \pm 3 \\
& B=100 \pm 10
\end{aligned}
\]

The product is \(\mathrm{P}=\mathrm{A} * \mathrm{~B}=1000\)
\[
\begin{aligned}
\sigma_{P} / P & =\left[(3 / 10)^{2}+(10 / 100)^{2}\right]^{1 / 2} \\
& =\left[(0.3)^{2}+(0.1)^{2}\right]^{1 / 2} \\
& =[0.09+0.01]^{1 / 2} \\
& =0.316 \\
& =3 / 10 \text { when rounded off } \\
& =\text { the largest fractional uncertainty }
\end{aligned}
\]

Rule - eliminate fractional uncertainties that are at least 3-times smaller, even if the magnitude of the uncertainty is larger.

\section*{Propagation of Errors}

\section*{Homework Exercises - Propagation of Errors}
1. Compute the combined uncertainties. Use formulas and show all work.
(a) \(x=1.2 \pm 0.1 \mathrm{~kg}, \mathrm{y}=48.76 \pm 0.12 \mathrm{~kg}\)
\[
\mathbf{z}=\mathbf{x}+\mathbf{y} \quad \text { Answer: } \mathbf{z}=
\]
\(\qquad\) \(\pm\) \(\qquad\) kg
(b) \(\mathrm{d}=600 \pm 30 \mathrm{~cm}\),
\(\mathrm{t}=0.118 \pm 0.006 \mathrm{~s}\)
\(\mathbf{v}=\mathbf{d} / \mathbf{t}\) Answer: \(\mathrm{v}=\) \(\qquad\) \(\pm\) \(\qquad\) \(\mathrm{cm} / \mathrm{s}\)
2. A standard container drum has a diameter \(D=20.6 \pm 0.2\) in and height \(H=38 \pm 1\) in.
(a) What is its volume and uncertainty.

Answer: V = \(\qquad\) \(\pm\) \(\qquad\) \(i n^{3}\)
(b) Express the answer in gallons (1 gal \(\equiv 231.0 \mathrm{in}^{3}\) ).

Answer: V = \(\qquad\) \(\pm\) \(\qquad\) gal```

